

Aerosol type classification using Depolarization Ratio derived by AERONET sun/sky radiometer data

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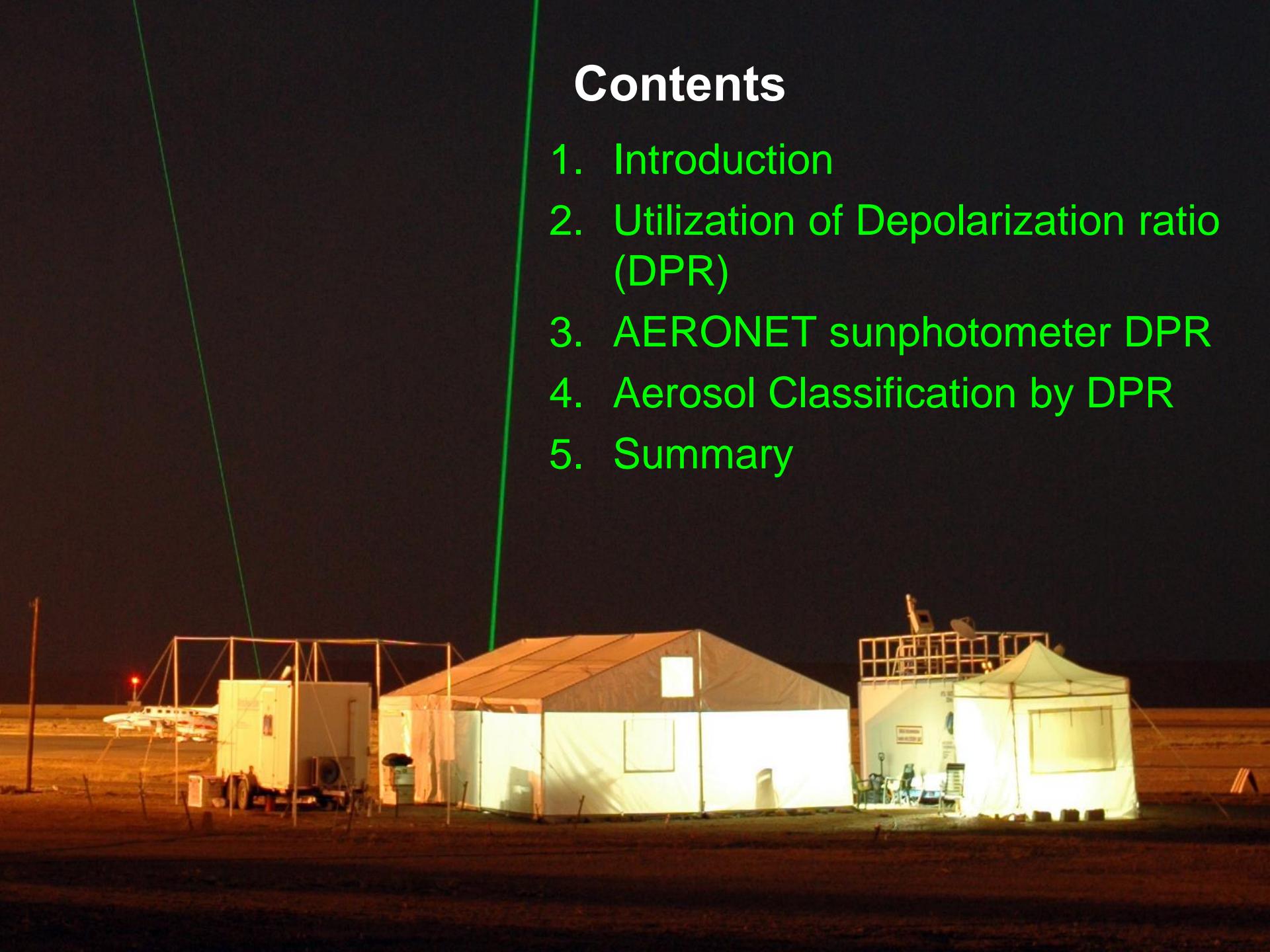
September 26, 2017

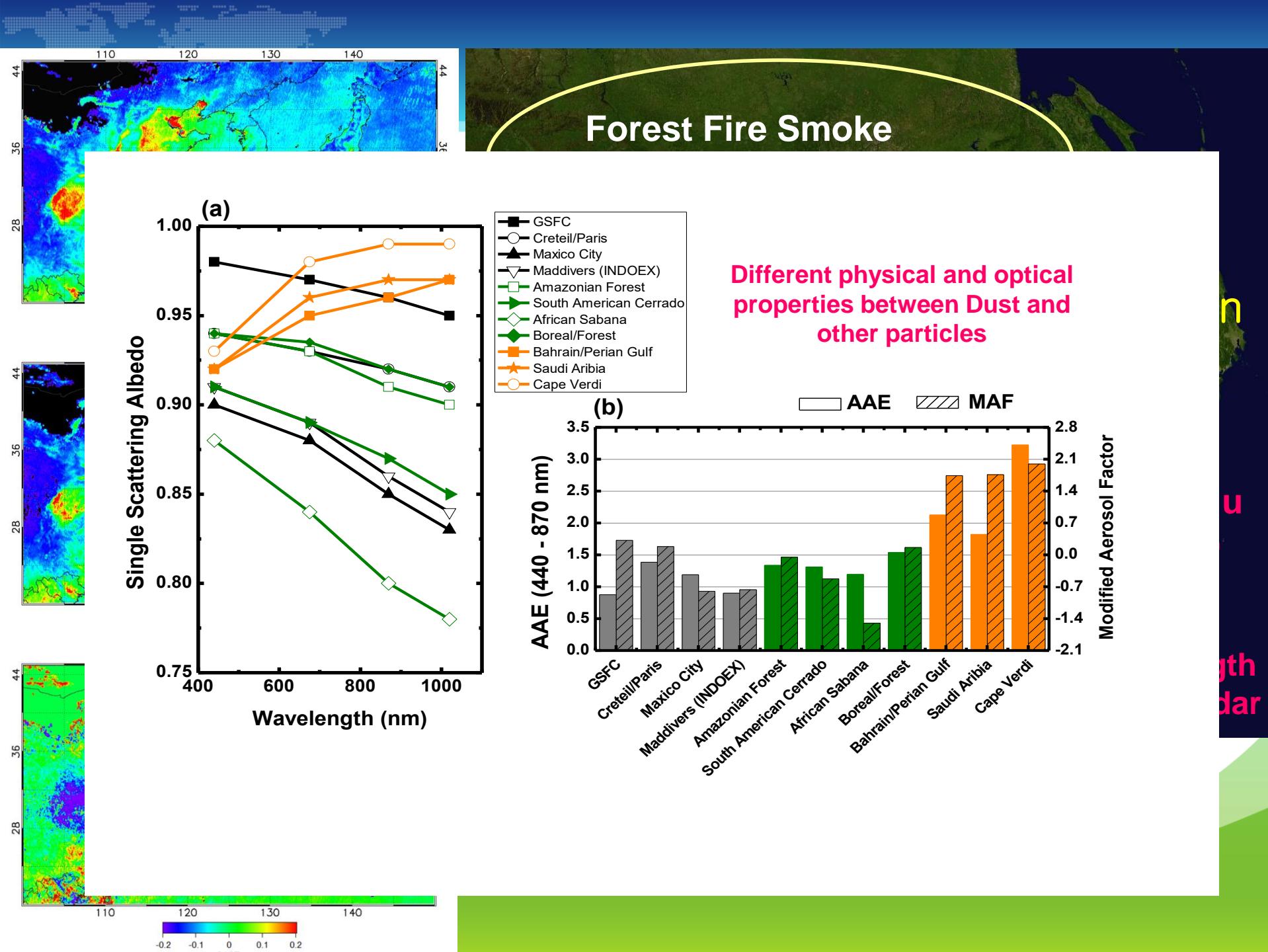


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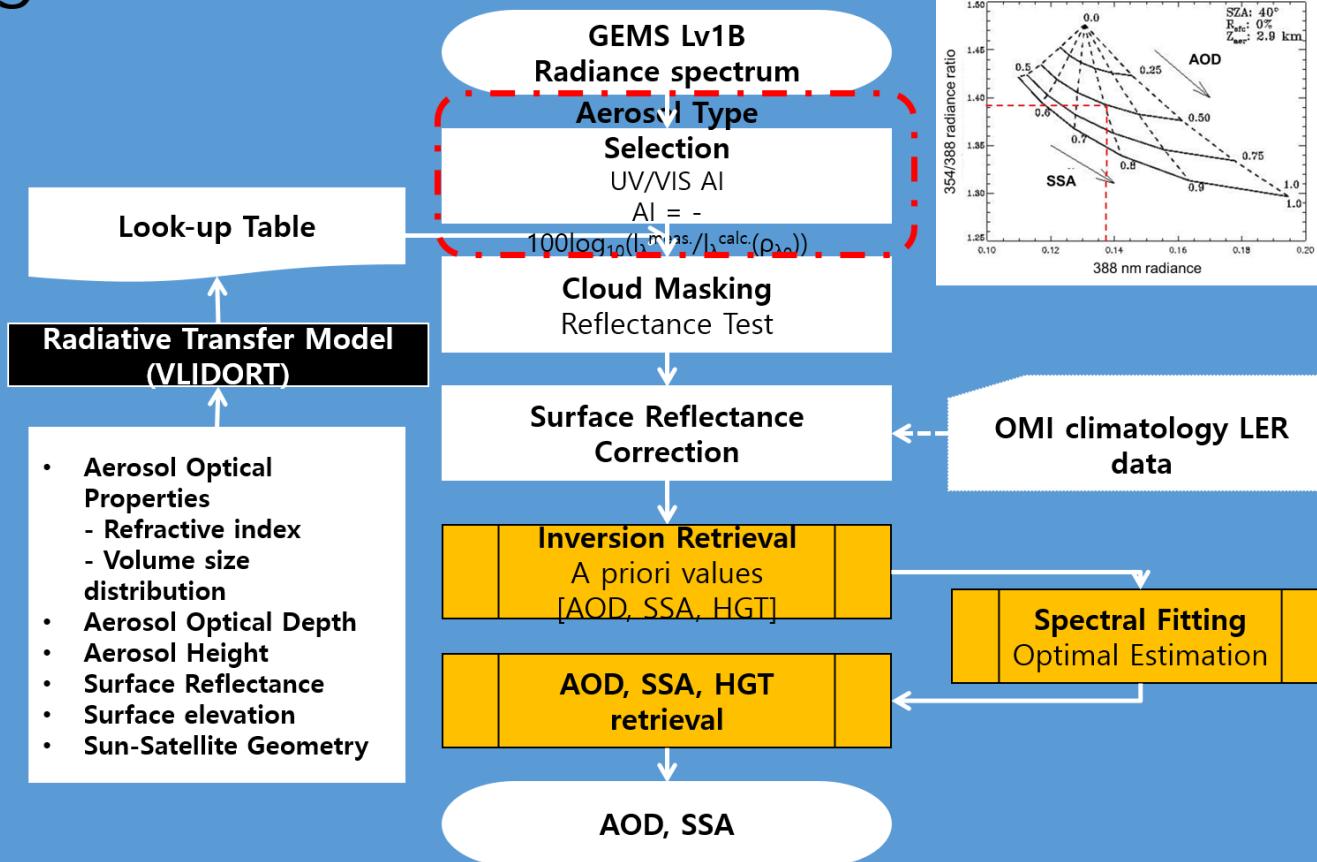
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2. Utilization of Depolarization ratio (DPR)
3. AERONET sunphotometer DPR
4. Aerosol Classification by DPR
5. Summary





AOD & SSA retrieval from SATELLITE Data

Algorithm Flowchart



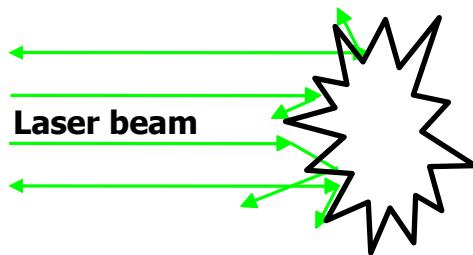
Aerosol type selection is very important

Depolarization Ratio

1. Depolarization ratio, definition : $\delta = I_{\perp}/(I_{\parallel} + I_{\perp})$,

Initial beam : I_{\parallel} (100 %)

2. The variation parameter of Aerosol Depolarization Ratio(DPR)
: Shape, Size, Moist, etc



Type 1: Nonspherical particle

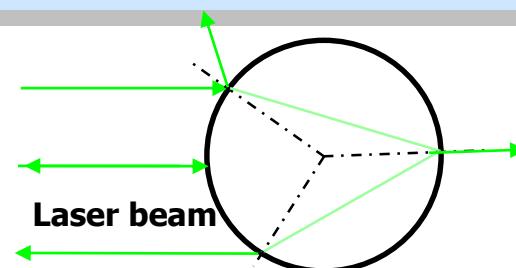
Asian dust : 0.3 ~ 0.35

Saharan dust 0.31

Mixed dust : 0.08~0.2 (Externally)

Cirrus cloud : 0.4

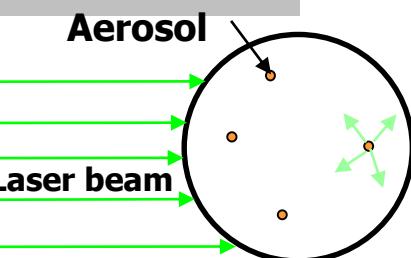
Sea salt : 0.02



Type 2 : Ideal spherical particle

DPR = 0

Sulphate : 0.04



Type 3: Internally mixed aerosol

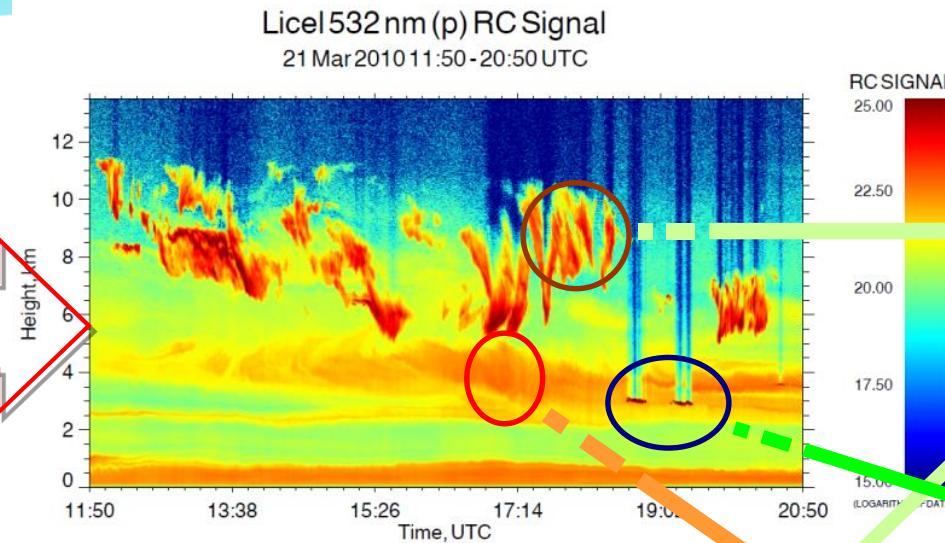
Hygroscopic aerosol

- DPR depends on the internal structure

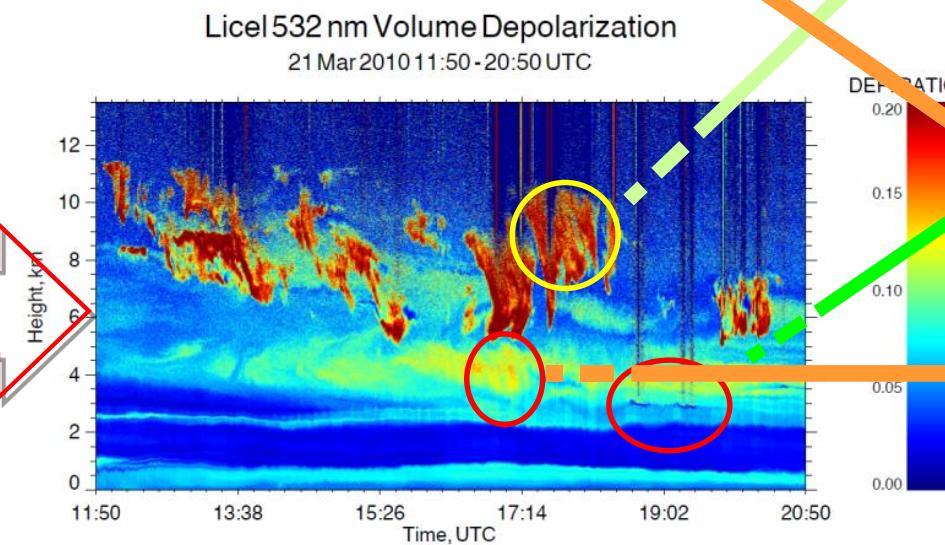
Aerosol Type Classification

Aerosol Type Classification by DPR

Range-corrected signal



Depolarization ratio



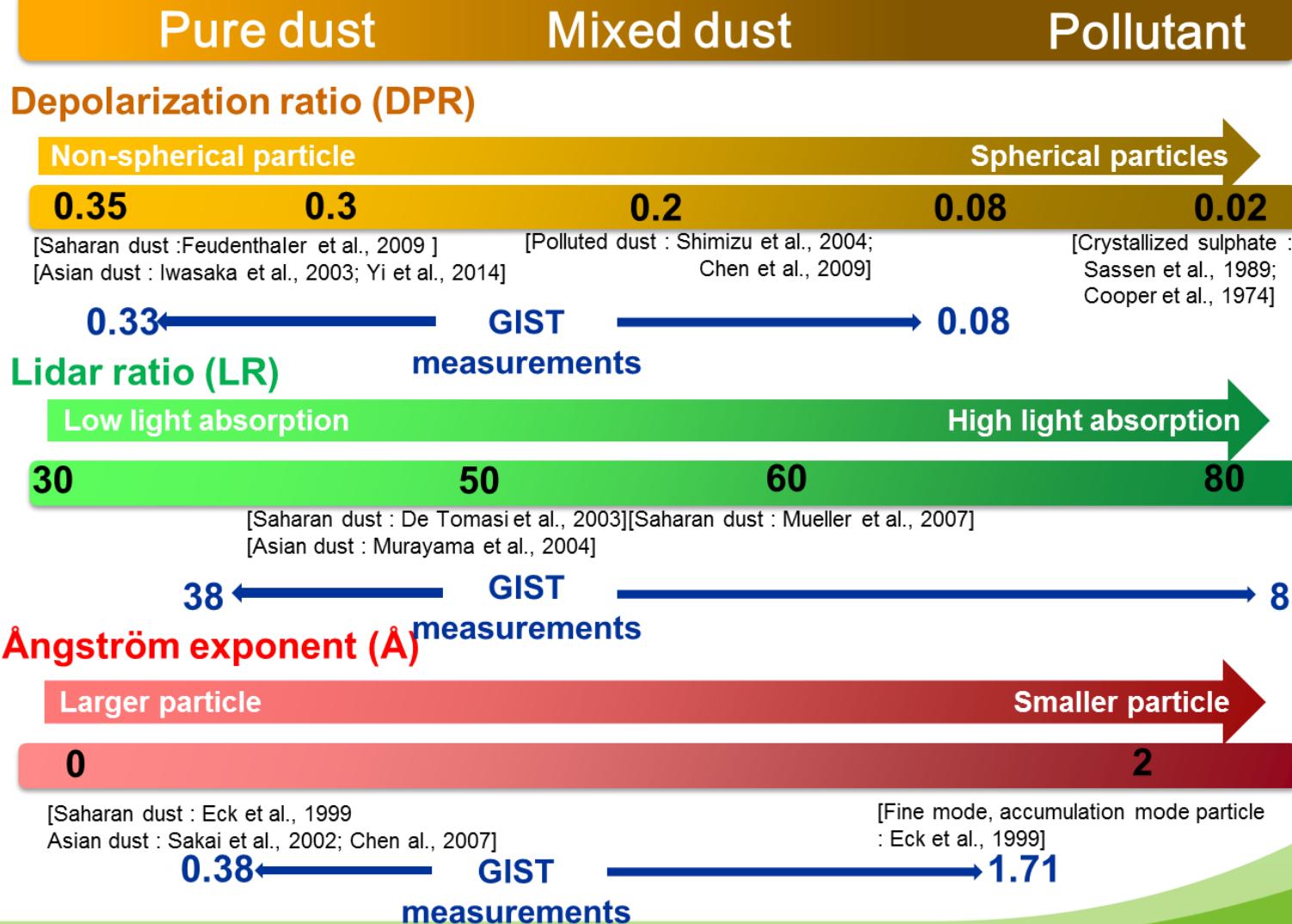
Cirrus Cloud

Cloud

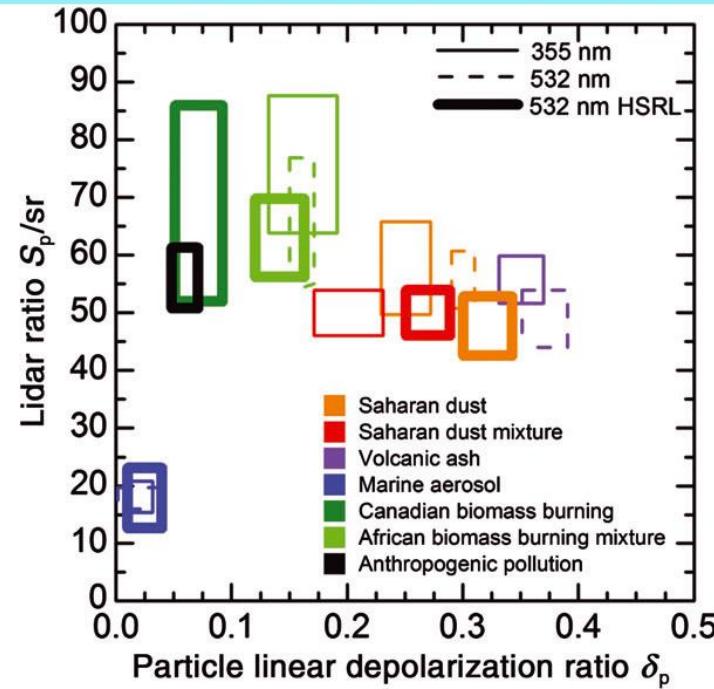
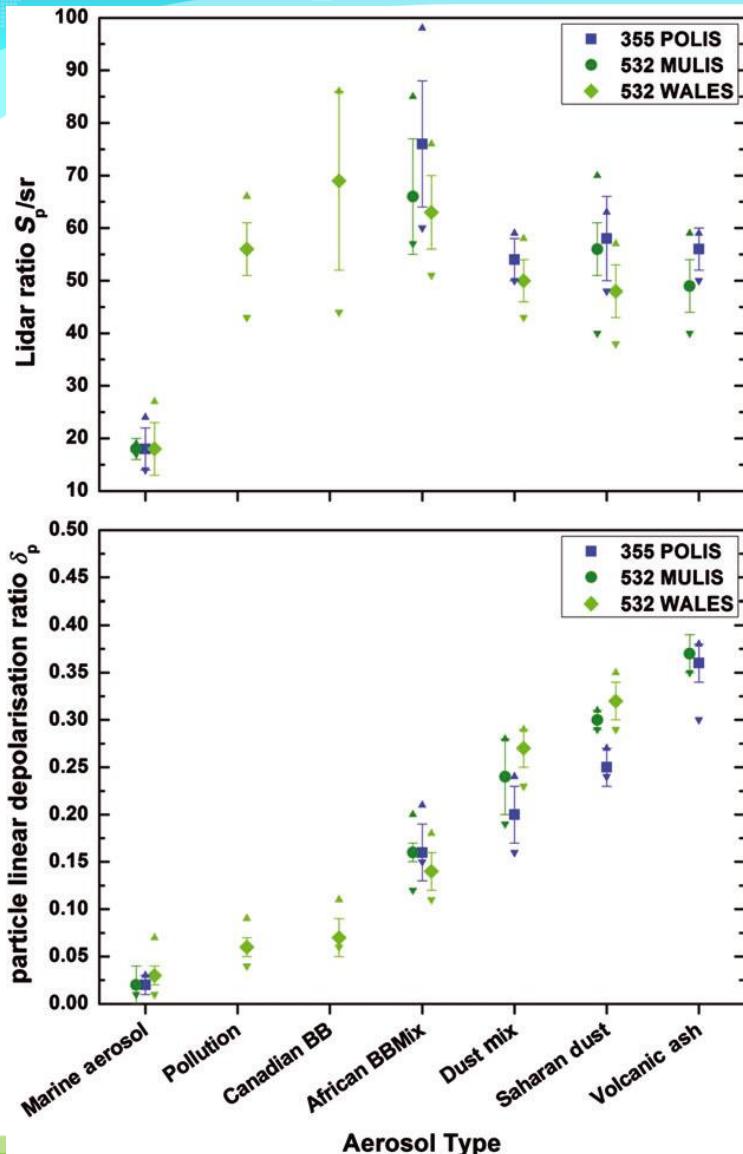
Dust

Value differences by mixing between dust and pollution

Optical properties of aerosol



AEROSOL Type Classification by DPR & LIDAR ratio



Five main Aerosol types
 : Mineral dust, mineral dust mixtures, Marine aerosols, biomass burning mixtures and volcanic ash

[Groß et al. (2015, Atmospheric Science Letters)]

Retrieval of Particle Depolarization Ratio

➤ LIDAR

$$\delta(z) = \frac{S(z)}{P(z) + S(z)}$$

δ : Volume depolarization ratio
 P : Initial laser beam
 S : Depolarized laser beam



$$\delta_p(z) = \frac{\delta(z)R(z) - \delta_m(z)}{R(z) - 1}$$

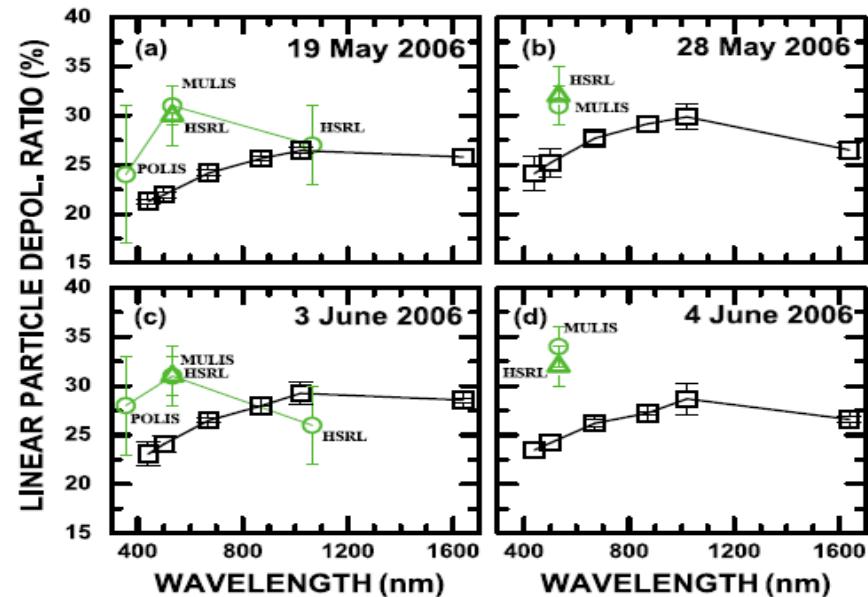
δ_p : Particle depolarization ratio
 $R(z)$: Scattering ratio
 δ_m : Depolarization ratio for air (0.014)

➤ Sunphotometer

$$\delta_p(\lambda) = \frac{1 - F_{22}(\lambda, 180^\circ) / F_{11}(\lambda, 180^\circ)}{1 + F_{22}(\lambda, 180^\circ) / F_{11}(\lambda, 180^\circ)} \times 100 (\%)$$

(Dubovik., 2006: JGR)

F11 and F22 (Müller scattering matrices) :
computed from the retrieved complex refractive indices and particle size distributions

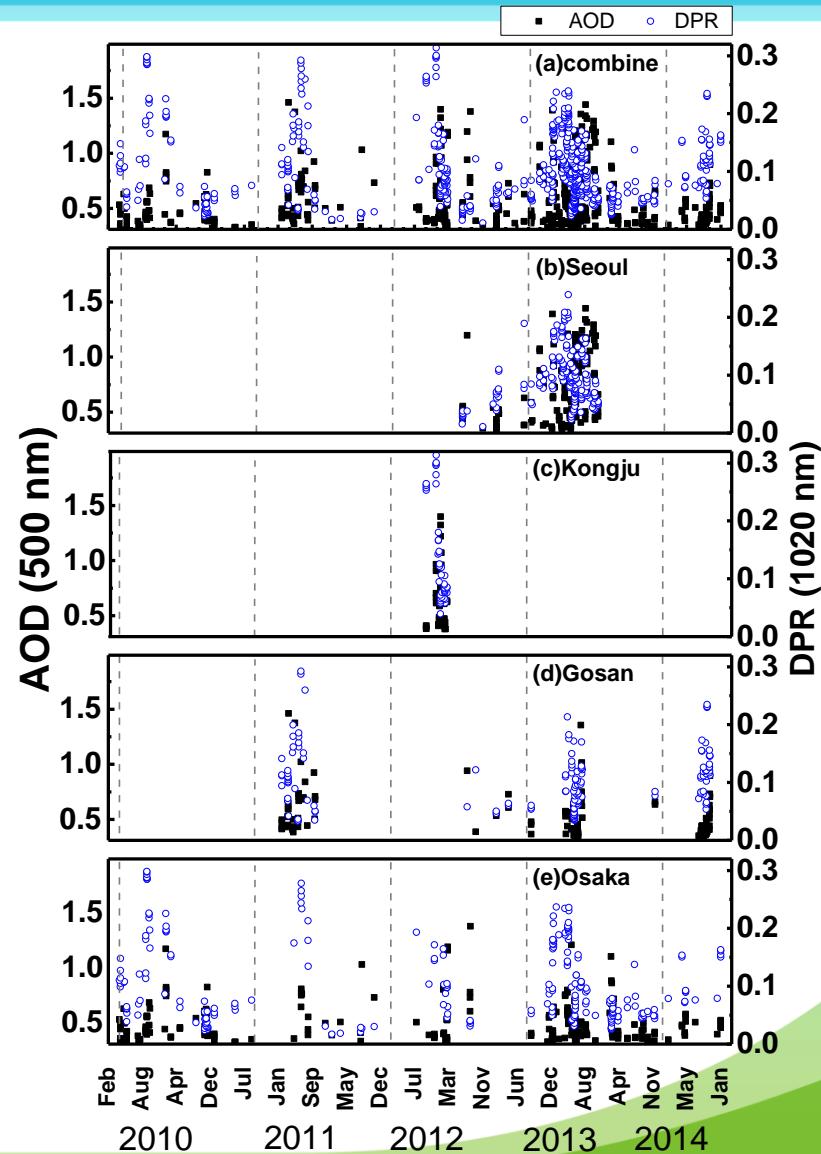
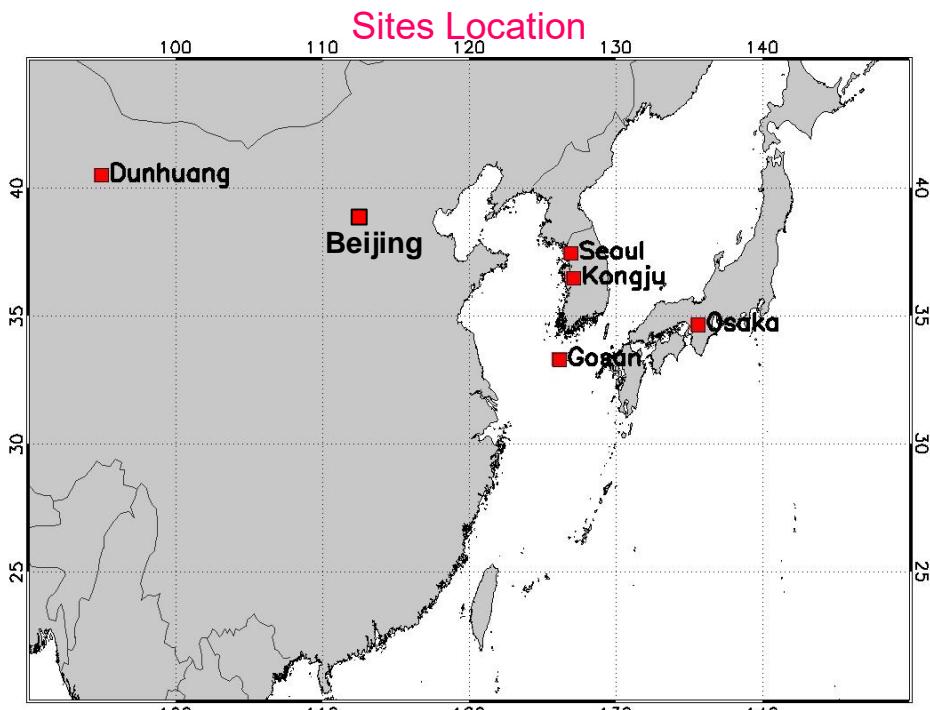


(Müller et al., 2012: JGR)

Depolarization comparison : Lidar & Sunphotometer

Analyzed Data: Observed at the same site and same time (2010 – 2014), Total 577 cases

- Seoul (160 cases), Kongju (44 cases), Gosan (139 cases), Osaka (234 cases)
- Dunhuang (12 cases, only Sunphotometer data, Pure dust cases)



Depolarization comparison : Lidar & Sunphotometer

LIDAR Depolarization Ratio (Vertical resolved data) → Column-integrated value

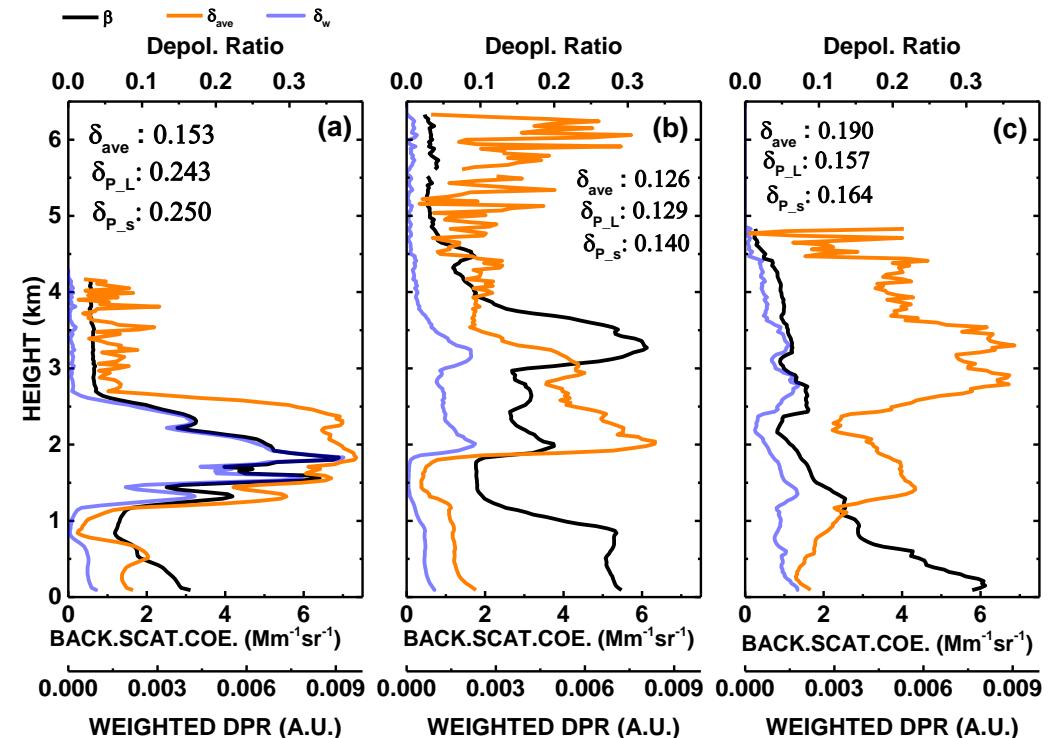
Column-integrated DPR (δ_{P_L})

$$\delta_{P_L} = \int_0^z \delta_P(z) W(z) dz$$

$W(z)$: Weight factor

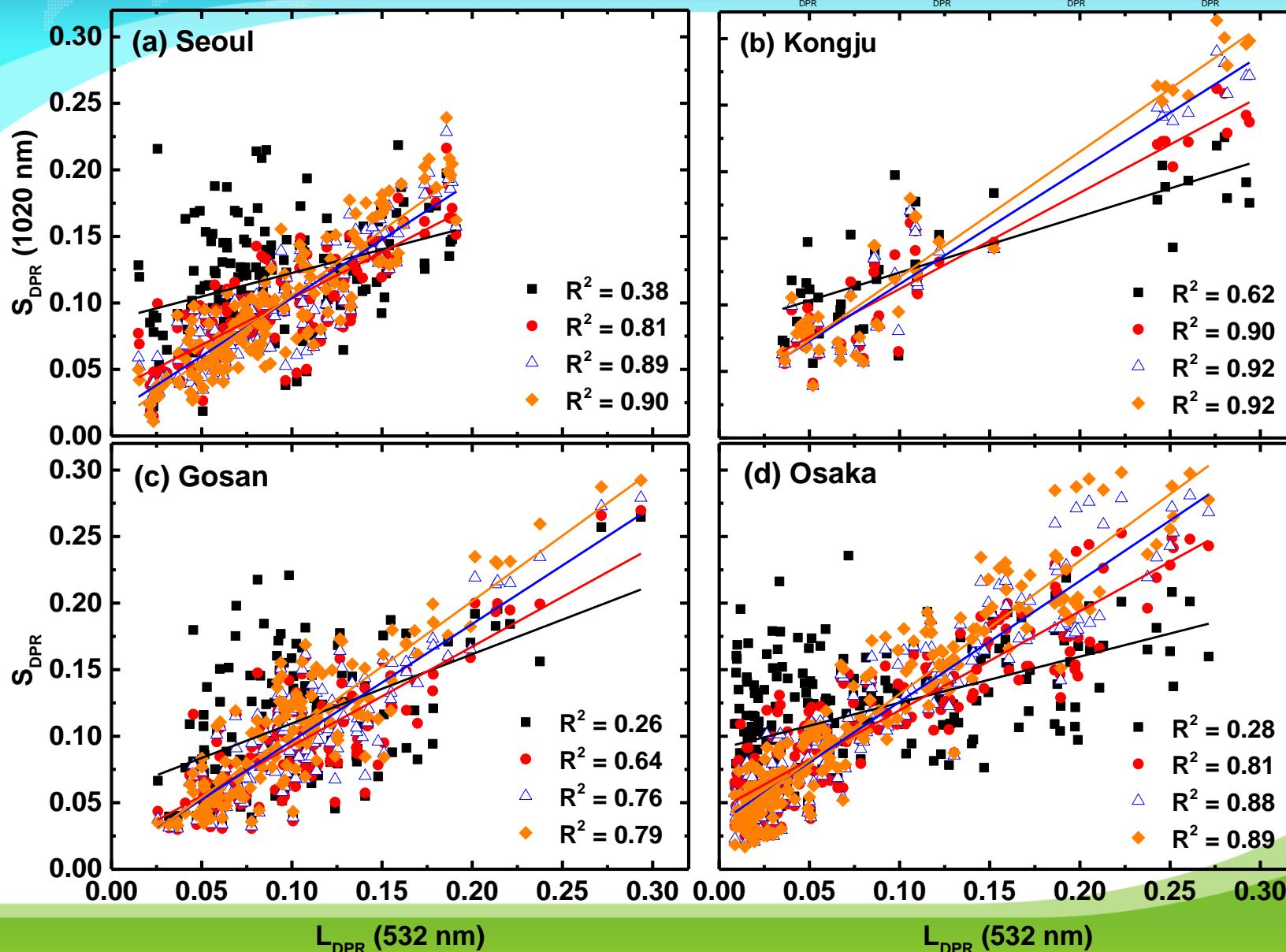
$$W(z) = \frac{\beta_a(z)}{\int_0^z \beta_a(z) dz}$$

β_a : aerosol backscatter coefficient
(LIDAR data)

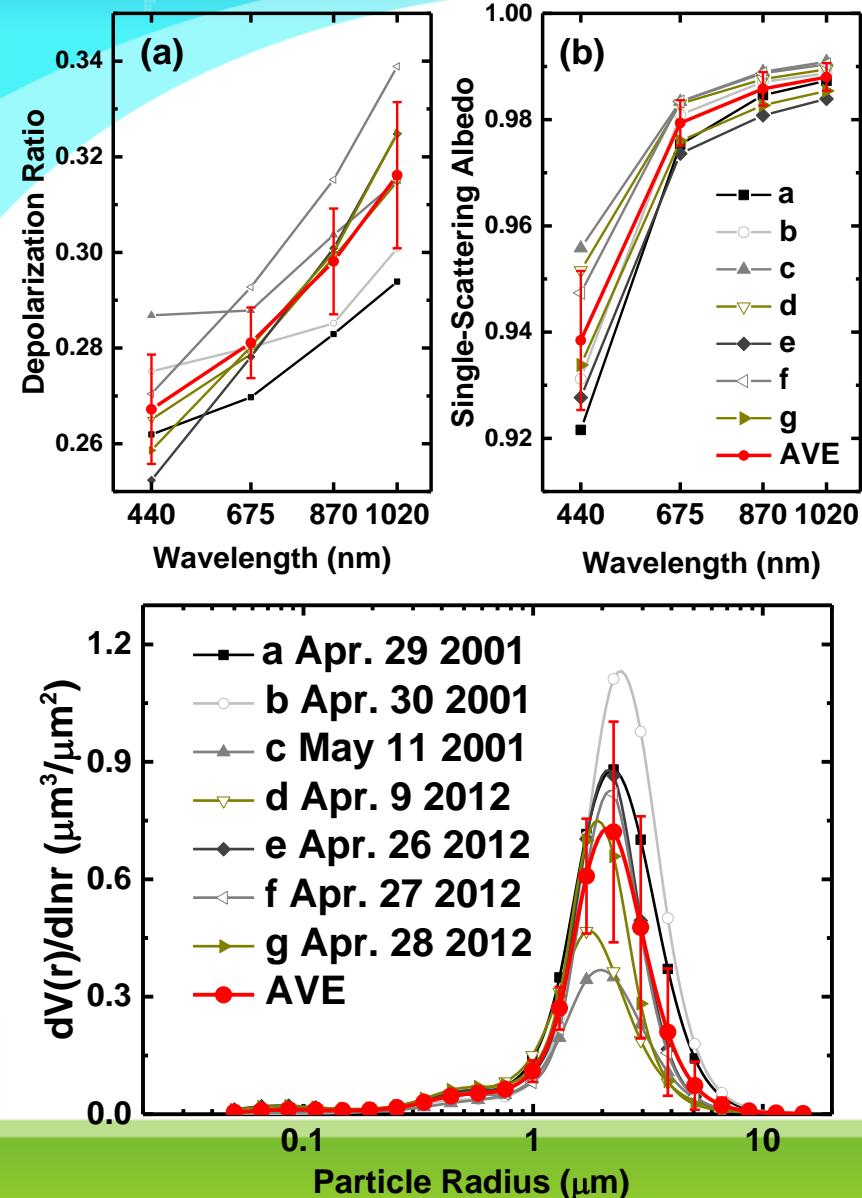


- Case I : High value of δ and high value of β
- Case II : Two aerosol layers, high value of only at above layer
- Case III : low value of β and high value of δ

Depolarization comparison : Lidar & Sunphotometer



Dunhuang (Dust Source region) Data (2001, 2012)



- 7 cases of Pure dust particles are selected
- Ave. value of DPR at 1020 nm : 0.32 ± 0.02

$$R = \frac{(\delta_a - \delta_2)(1 + \delta_1)}{(\delta_1 - \delta_2)(1 + \delta_a)}$$

R : Dust ratio (0 ~ 1)
 δ_1 : 0.32, assumed value for pure dust
 δ_2 : 0.02, pure pollution
 → Empirical data by long-term lidar measurements

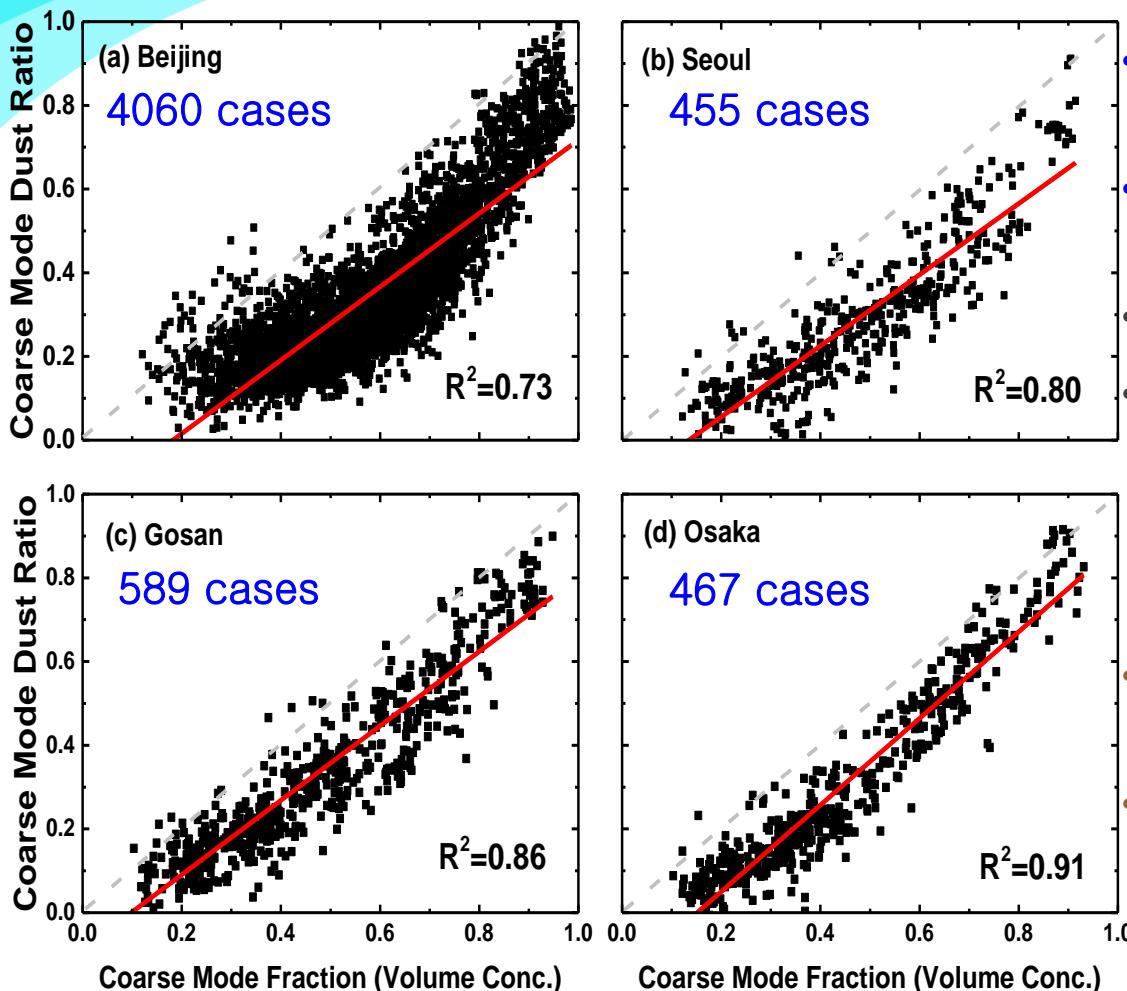
[Shimizu et al. (2004), Tesche et al. (2009), Noh et al. (2014)]

Dunhuang Average value

- Dust ratio : 0.98 ± 0.03
- Coarse-mode fraction by volume concentration : 0.95 ± 0.02

Comparison between Dust ratio and Coarse-mode fraction

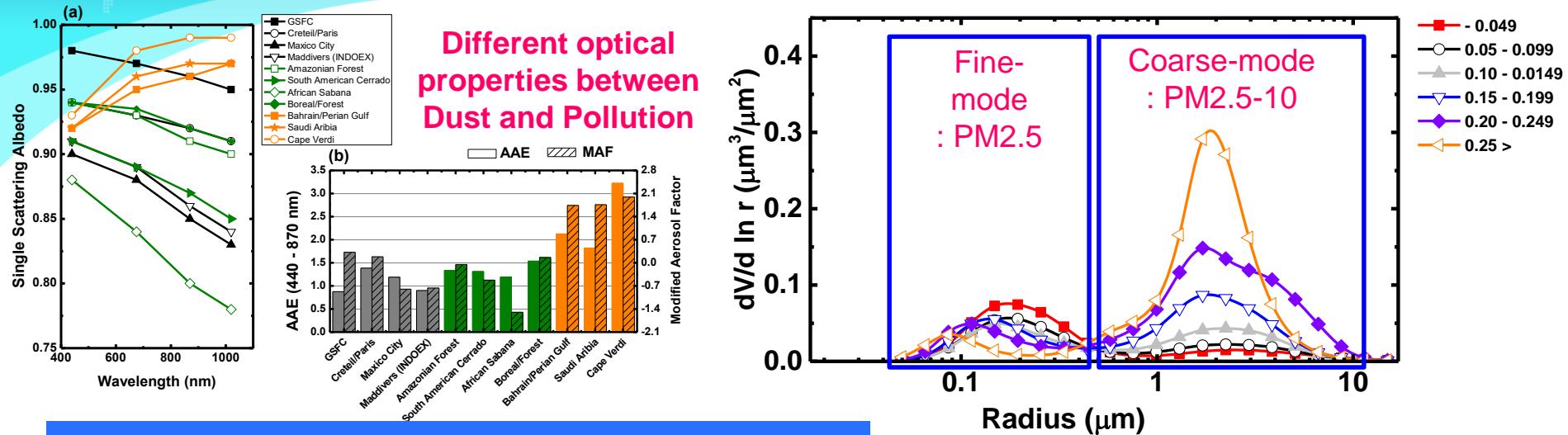
Total 5561 cases



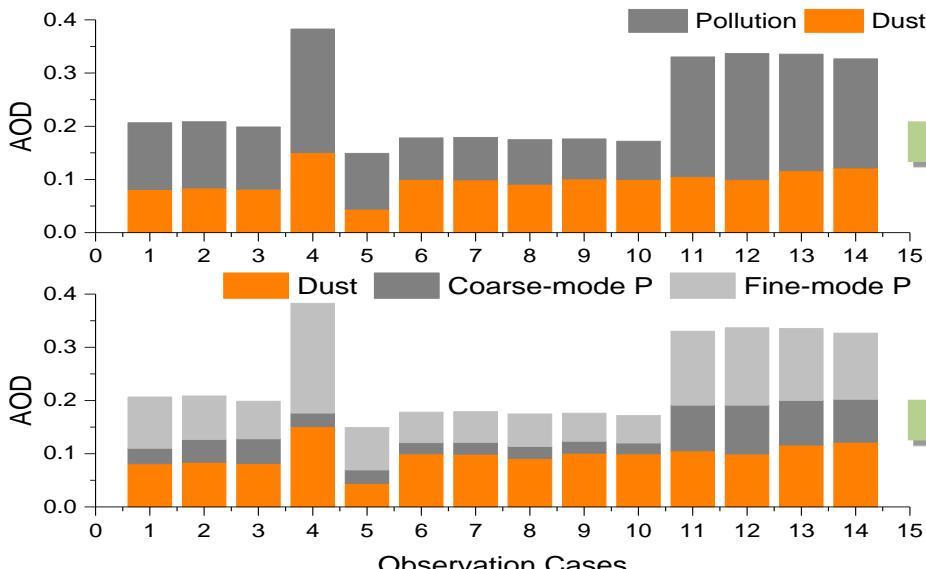
- **Dust ratio (R_D)** : the ratio of dust particle to pollution particles
 - **Coarse-mode fraction (CMF)** : only related to particle size
 - CMF is higher 10 – 20 % than R_D
 - CMF and R_D show similar value at Dunhuang
-
- All coarse-mode particle is not dust particle
 - Size parameter has high uncertainty to classify aerosol type

Year 2001 ~ 2016

Aerosol Separation as Asian dust, PM10, PM2.5



Separation of Aerosol Concentration

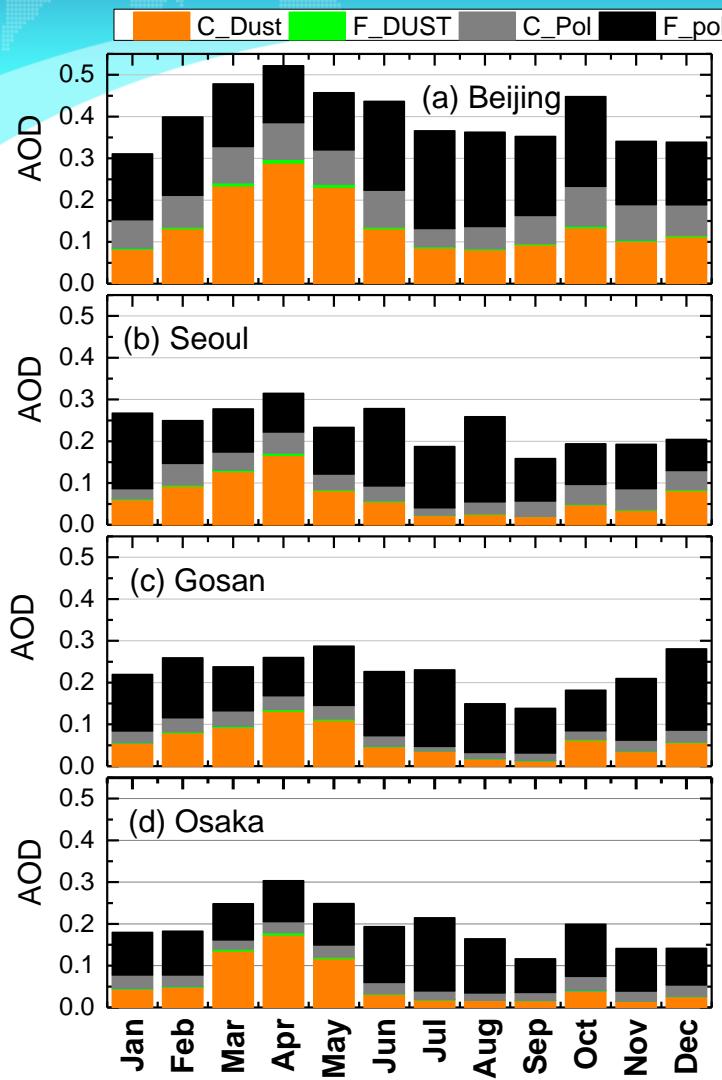


Dust and Pollution particle using only Dust ratio

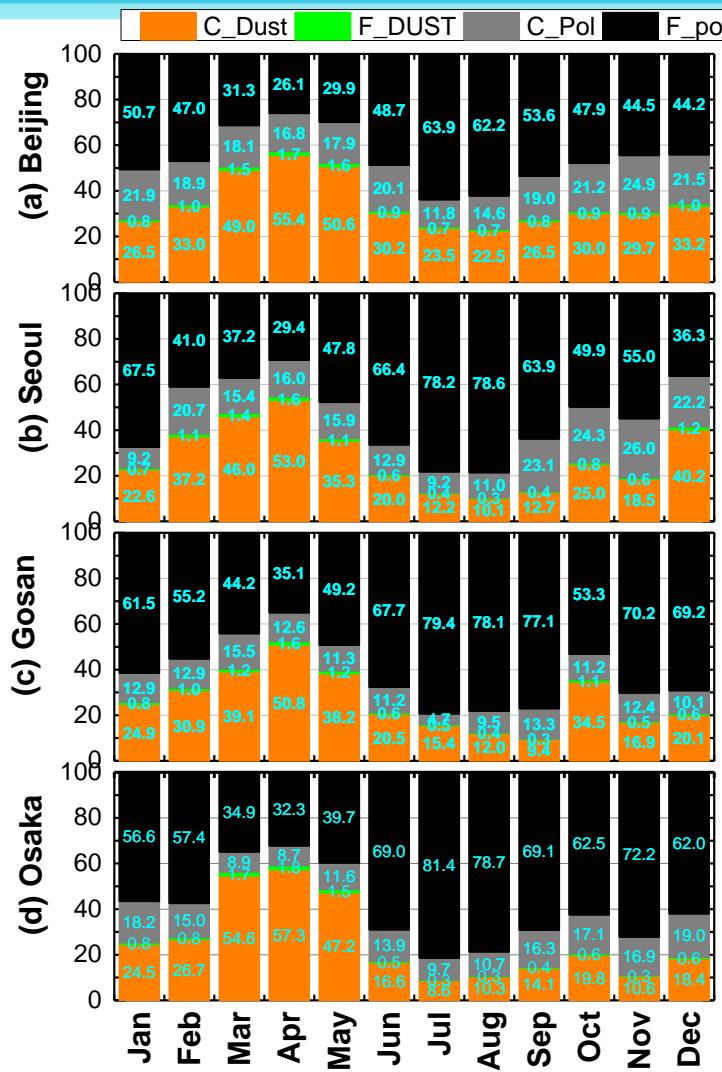
Separation as Dust, PM10 and PM2.5 using Dust ratio & Size distribution

PM2.5 = Fine-mode pollution
PM2.5-10 = Dust+Coarse-mode Pollution

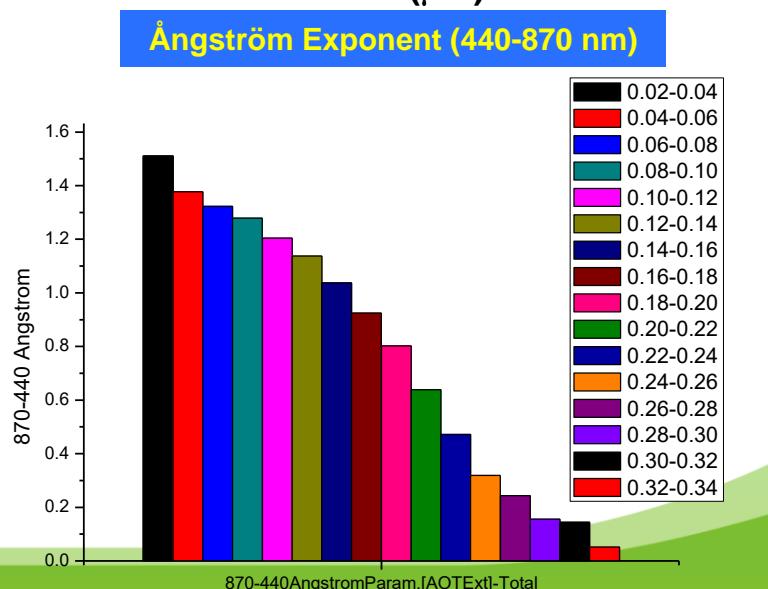
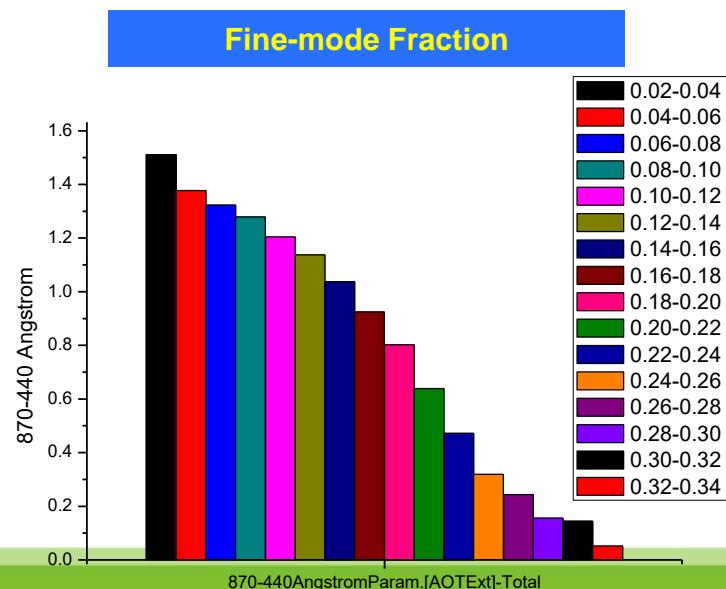
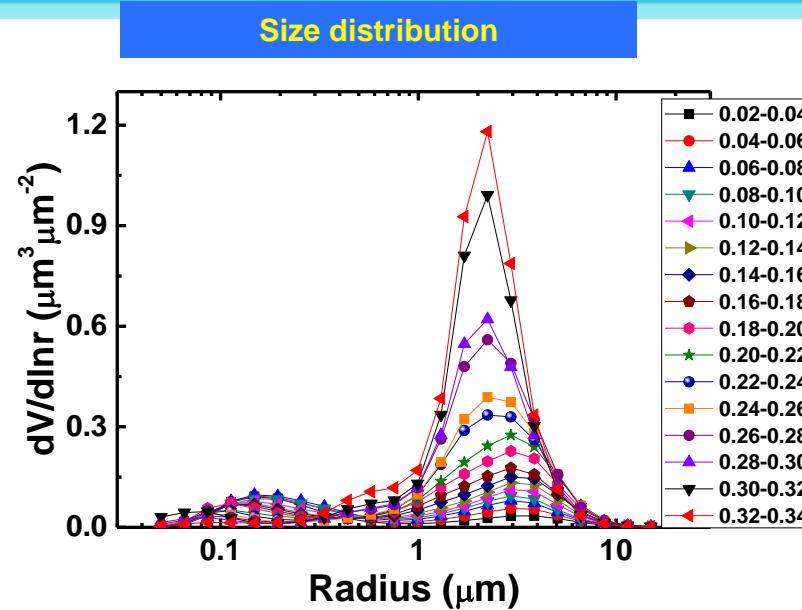
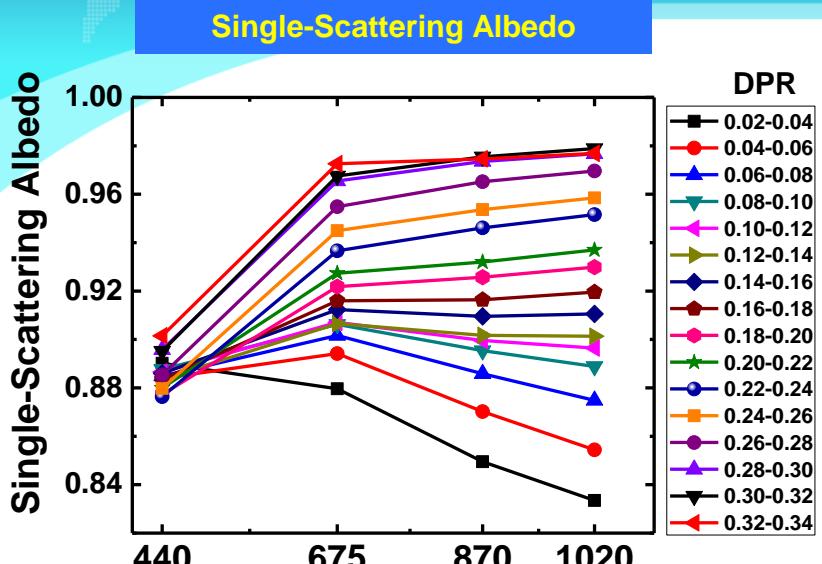
Seasonal variation of Dust and Coarse-mode pollution particle



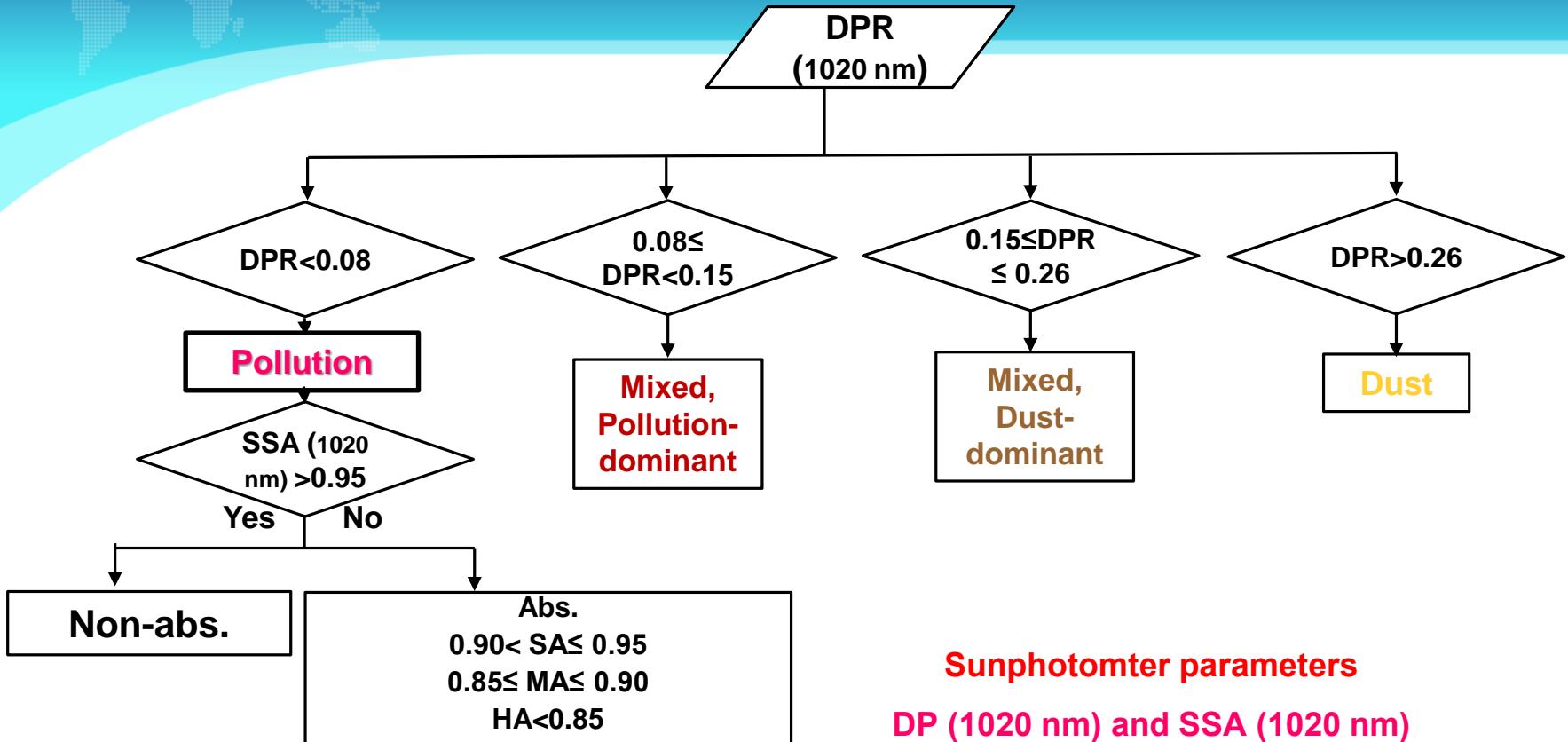
AOD : 1020 nm



Variation of Optical Parameter (Beijing)

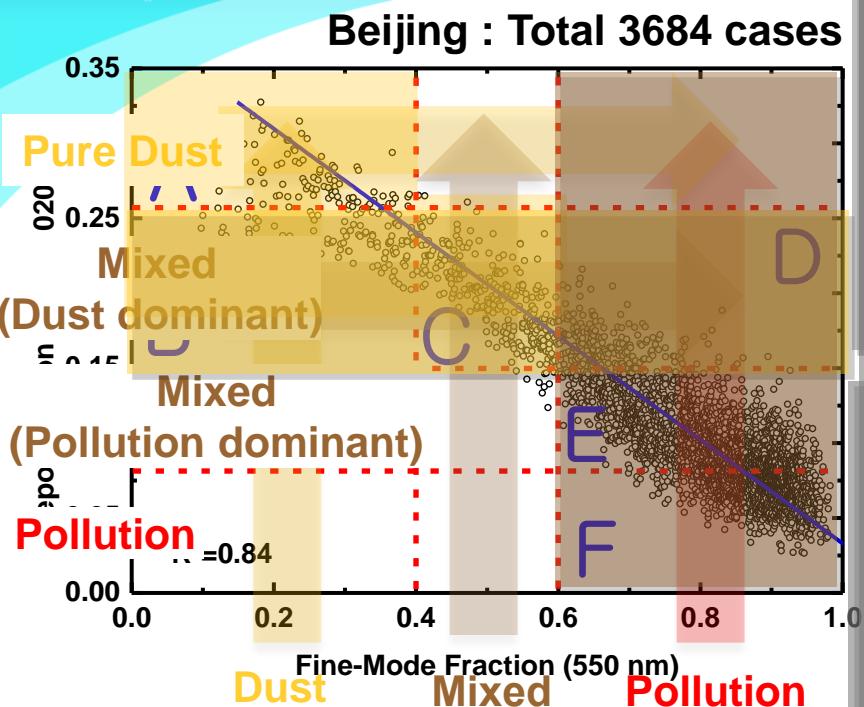


Flowchart of the aerosol classification algorithm



- Dust aerosols (DPR to be greater than 0.26)
- Dust-dominant ($0.15 \leq \text{DPR} \leq 0.26$)
- Pollution-dominant ($0.08 \leq \text{DPR} < 0.15$)
- Pollution aerosols (DP to be less than 0.08)
- The HA, MA, SA, and NA represent highly-absorbing, moderately-absorbing, slightly-absorbing, and non-absorbing aerosols, respectively

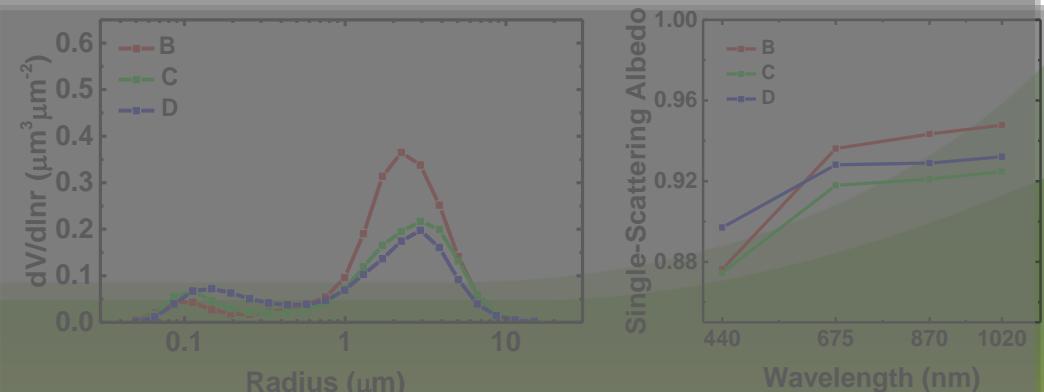
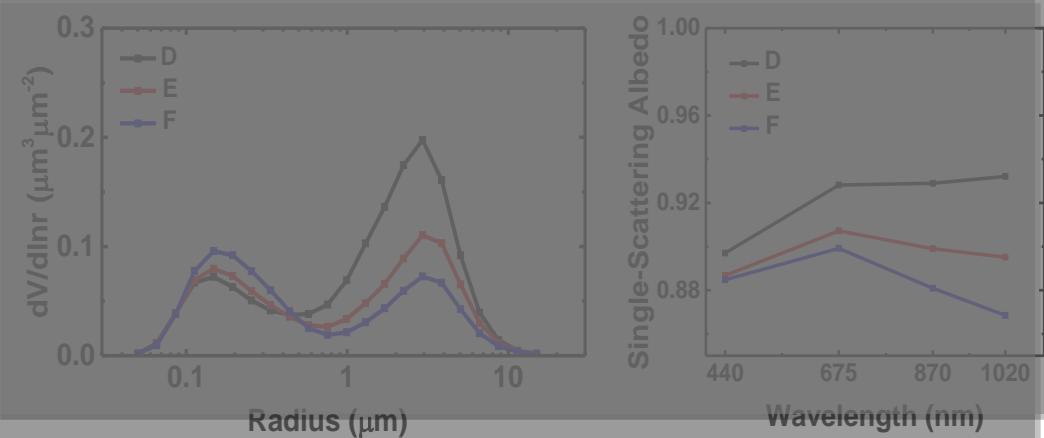
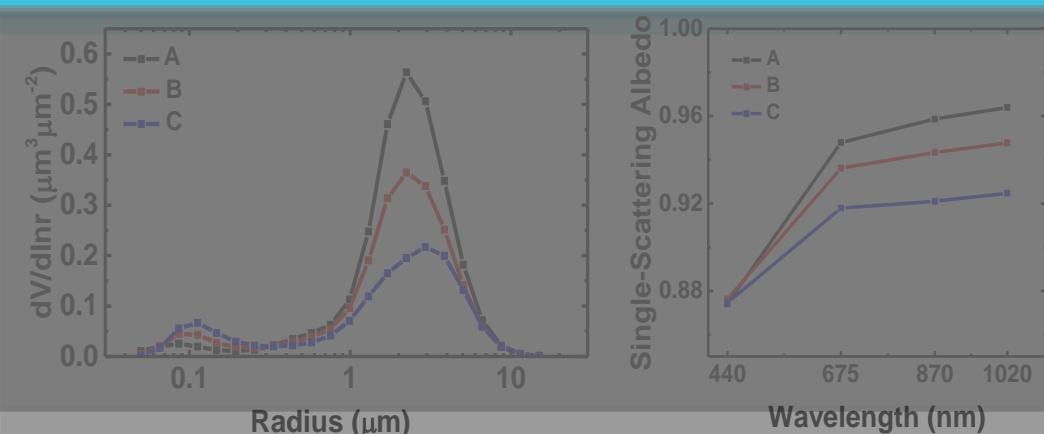
Comparison Between two Methods



Aerosol type classification by size information

- Pollution (FMF > 0.6)
- Dust (FMF < 0.4)
- Mixture (between 0.4 and 0.6)

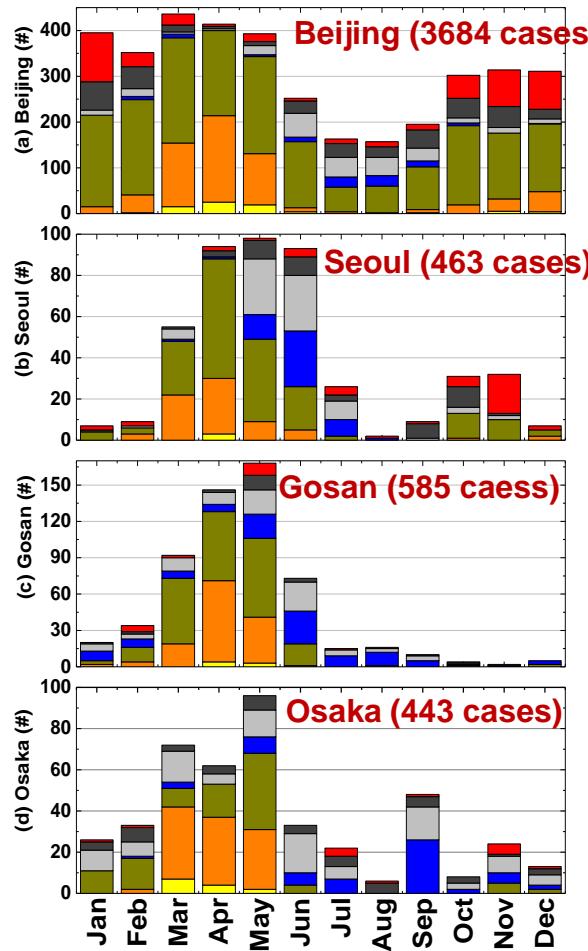
FMF at 550 nm
(Lee et al., 2010)



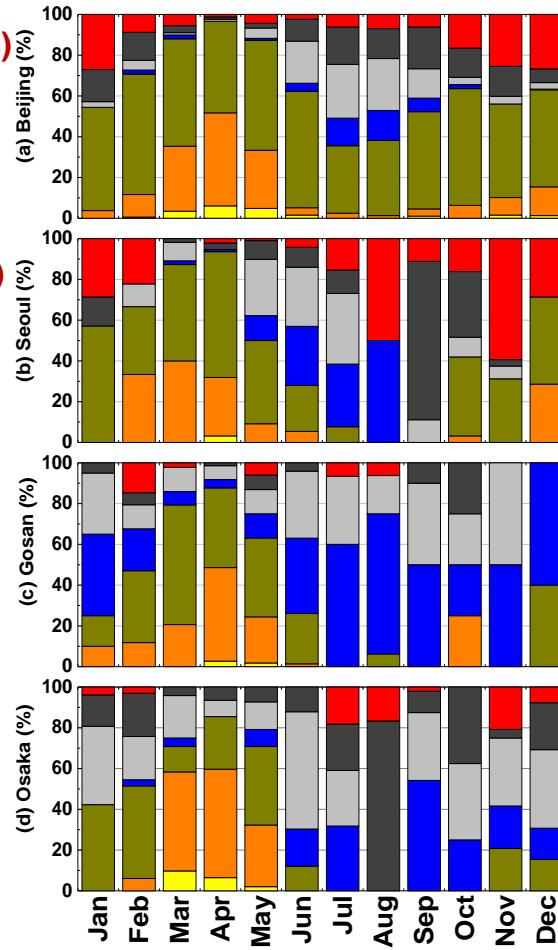
Aerosol Type Classification

(Dust, Mixed (Dust, Pollution), Pollution)

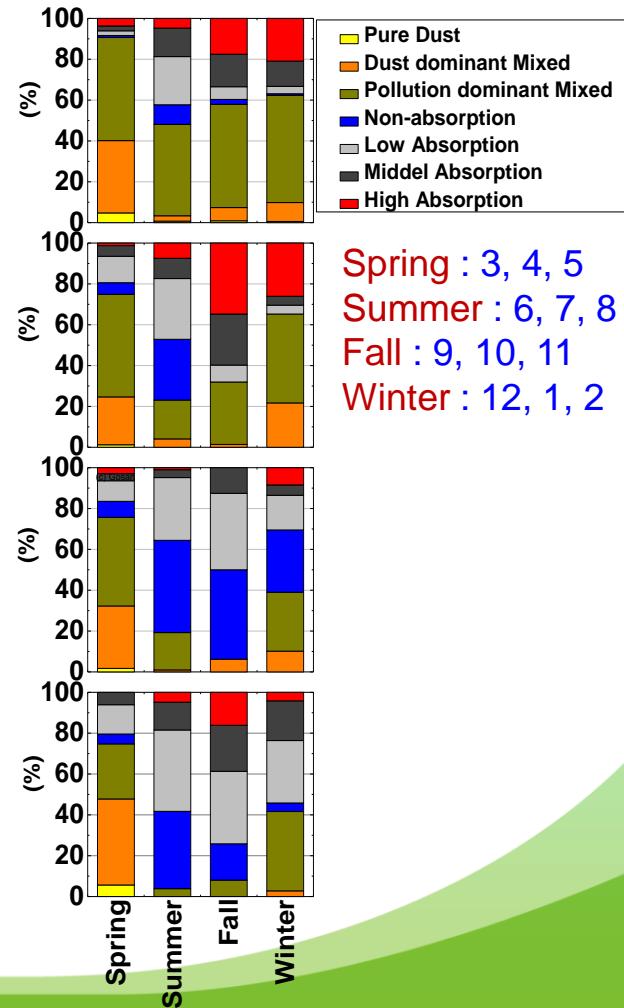
Numbers per Types



% according to Types



Seasonal %





Summary

- We investigated the reliability of depolarization ratio derived by AERONET sunphotometer.
- The strong correlation between lidar and sunphometer depolarization were obtained as 0.90, 0.92, 0.79, and 0.89 at Seoul, Kongju, Gosan and Osaka, respectively.
- Sunphotometer depolarization ratio can provide comparably reliable information to identify the presence of Asian dust particles in the mixed aerosol plumes.
- Depolarization ratio is more effective to classify aerosol type than only using size information parameters.

Thank you for your listening



